SUMMARY



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ANTI-COLLISION SYSTEM

WIRING TERMINAL STRIPS

The anti–collision system must be connected to terminal strip X of the crane control panel according to the following table:

Terminals of terminal strip X	Signal	Description
1–2	Contact NO	Cutoff of slewing to the left
3–4	Contact NF	White flashlight
5–6	NO contact	Cutoff of slewing to the right
7	OV	Deceleration of slewing
8	Sortie 4–20 mA	Deceleration of slewing
9–10	Contact NO	Deceleration of trolley out movement
11–12	Contact NO	Cutoff of trolley out movement
13–14	Contact NO	Slewing brake
15–16	Contact NO	Cutoff of trolley in movement
	Contatto NO	
17	Sortie d'alimentation 24VDC	Neutral position
	Uscita alimentazione 24VDC	
18	Entrée logique	Neutral position
19–20	Contact NO	Deceleration of trolley in movement
21–22	Contact NO	Forward traveling movement cutoff
23–24	Contact NO	Backward traveling movement cutoff
25–26	Contact NO	Hoisting cutoff
27–28	Contact NO	Lowering cutoff
29	Entrée logique 48VAC ou 24VDC	Weathervaning
30	-	Fixing

MEANING OF INTENSITIES MEASURED AT TERMINAL X.8

Intensity between X7 and X8	Description
0 mA	No deceleration
5 mA	Deceleration to the right
10 mA	Deceleration to the left
20 mA	Deceleration to the right and to the left

21-12-17

WIRING DIAGRAMS





Tolerance of intensity measured at terminal X8: <+1 mA.

For TT2 or MC602 systems, the consistency check must be activated and carried out on a daily basis. Returned to = "TOP TRACING 2" system / Programming – Calibration.

For systems other than TT2 or MC602, the system cutoffs must be redundant by means of an Emergency Stop cutoff wired in series with the Emergency Stop line of the crane (e.g. on BR4-4, BR4-5 or BR4-19).

Systems other than TT2 or MC602 must use their own sensors.